

Advanced Computer Graphics

Generalized Barycentric Coordinates

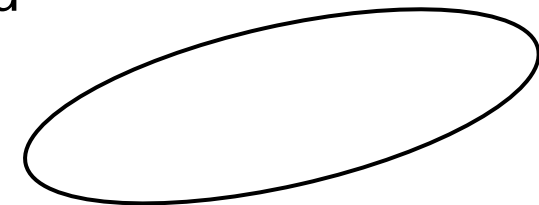
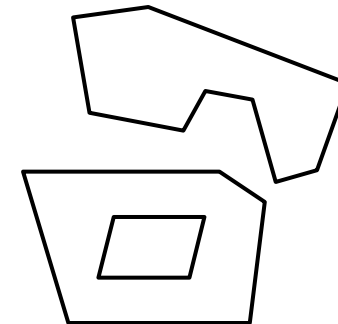
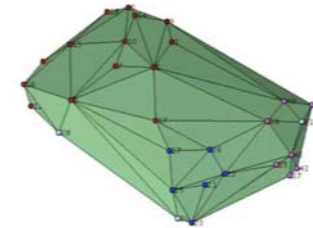
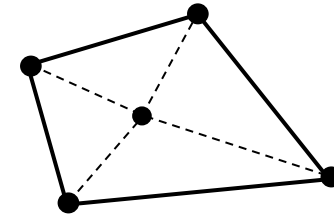
G. Zachmann

University of Bremen, Germany

cgvr.informatik.uni-bremen.de

Generalized Barycentric Coordinates

1. What does one do with (convex) 2D polygons with $k > 3$ sides?
2. Similarly, what does one do with polyhedra in n dimensions with $k > n+1$ sides? (i.e., non-simplices)
3. What does one do with non-convex (concave) areas?
4. What does one do when the area is not limited by a polyline (piecewise linear curve), but rather by a smooth, closed convex curve?



- Definition:

Let Ω be a convex polygon in \mathbb{R}^2 with n vertices

P_1, \dots, P_n , $n \geq 3$, in CCW arrangement ("*counter-clockwise*").

A set of functions $\lambda_i : \Omega \rightarrow \mathbb{R}$ are called **barycentric coordinates** if for all $X \in \Omega$ the following conditions are met:

1. Partition of unity:
$$\sum_{i=1}^n \lambda_i(X) = 1$$

2. Linear precision:
$$\sum_{i=1}^n \lambda_i(X) P_i = X$$

3. Convex combination:
$$\forall i = 1 \dots n : \lambda_i(X) \geq 0$$

- Other desirable characteristics:
 - "Good behavior" with respect to the area outside of Ω
 - Smoothness: λ_j should be in C^∞
 - Affine invariance

The Interpolation Property

- Theorem:

Any such (generalized) barycentric coordinates have the **interpolation property**.

That is: let data values f_i be given in the vertices P_i ; then the function

$$f(X) = \sum_{i=1}^n \lambda_i(X) \cdot f_i$$

is actually an interpolating (and not simply approximating) function; it follows that

$$\forall i : f(P_i) = f_i$$

- We will show:

$$\lambda_i(P_j) = \delta_{ij} \quad (\text{Kronecker Delta})$$

1. Because of properties 1 and 2, one can reproduce **all linear** functions using barycentric combinations:

Let $f(Q)$ be just such a linear function.

Then

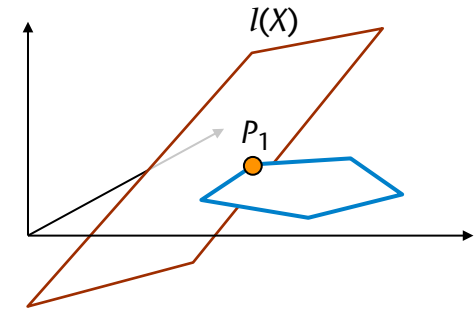
$$\begin{aligned}
 f(Q) &= \begin{pmatrix} a \\ b \end{pmatrix} Q + c && \begin{array}{l} \text{Prop. 2} \\ \text{(lin. prec.)} \end{array} \\
 &= \begin{pmatrix} a \\ b \end{pmatrix} \sum \lambda_i(Q) P_i + c \sum \lambda_i(Q) && \begin{array}{l} \text{Prop. 1} \\ \text{(partition of unity)} \end{array} \\
 &= \sum \lambda_i(Q) \left(\begin{pmatrix} a \\ b \end{pmatrix} P_i + c \right) \\
 &= \sum \lambda_i(Q) f(P_i)
 \end{aligned}$$

2. We define plane $l(X)$ so that

$$l(P_1) = 0$$

$$\forall i \geq 2 : l(P_i) > 0$$

This is possible because Ω is a **convex** polygon



3. From step 1, it follows that:

$$l(P) = \sum_{i=1}^n \lambda_i(P) \cdot l(P_i) = \sum_{i=2}^n \lambda_i(P) \cdot l(P_i)$$

$\leftarrow l(P_1) = 0$

l was specially chosen so that

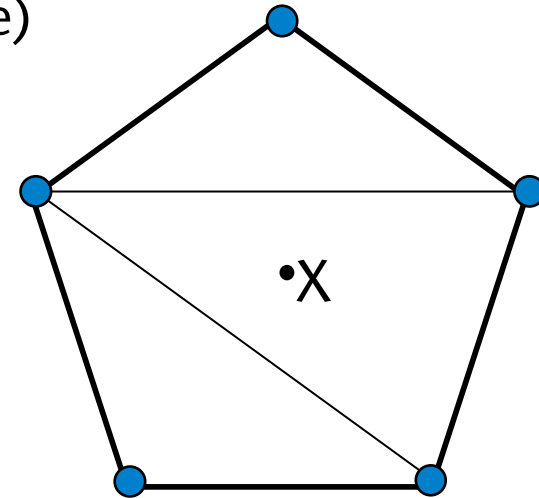
$$0 = l(P_1) = \sum_{i=2}^n \lambda_i(P_1) l(P_i) \Rightarrow \forall i \geq 2 : \lambda_i(P_1) = 0$$

$\uparrow l(P_i) > 0$

4. Because of property 1: $1 = \sum_{i=1}^n \lambda_i(P_1) = \lambda_1(P_1)$

\leftarrow (step 3)

- Triangulate the polygon (in any way possible)
 - Determine the barycentric coordinates with reference to the triangle in which X is located
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- Problems:
 - The triangulation is not unique
 - These generalized barycentric coordinates are **not unique!**
 - These barycentric coordinates are only C^0 -continuous
 - The extension for points outside of the polygon is unclear



- Goal: construct barycentric coordinates for any convex polygon in 2D
- Observation: since $\sum \lambda_i = 1$, we have

$$\sum \lambda_i P_i = X \Leftrightarrow \sum \lambda_i \cdot (P_i - X) = 0$$

- If one has functions $w_i = w_i(X)$ for which the following two properties hold,

$$\sum w_i \cdot (P_i - X) = 0 \quad (1)$$

$$\text{und } \forall i : w_i \geq 0 \quad (2)$$

then one can easily make "real" barycentric coordinates by just letting

$$\lambda_i = \frac{w_i}{\sum_{i=1}^n w_i}$$

- Look for functions w_i that fulfil conditions (1) & (2)

- Surface areas:
 - $r_i := \|P_i - X\|$
 - $A_i := A_i(X) = \frac{1}{2} \sin \alpha_i \cdot r_i r_{i+1}$
 $= \mathcal{F}(\Delta X P_i P_{i+1})$
 - $B_i := B_i(X) = -\frac{1}{2} r_{i-1} r_{i+1} \sin(\alpha_{i-1} + \alpha_i)$
 $= \mathcal{F}(\Delta X P_{i+1} P_{i-1})$
 - Note: the sign of B_i is *negative*,
 if X is outside of $\Delta P_{i-1} P_i P_{i+1}$
 - $C_i := C_i(X) = \mathcal{F}(\Delta P_{i-1} P_i P_{i+1})$
 $= A_i + A_{i-1} + B_i$
- Indices: in the following, all indices are meant to be "modulo n ", i.e. $P_i := P_{i \bmod n}$ and so $P_{n+1} = P_1$, $P_{-1} = P_{n-1}$

